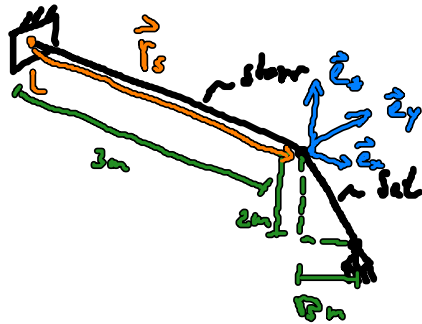


Kraftvektor

Basisvektoren

$$\vec{F} = \begin{pmatrix} F_x \\ F_y \\ F_z \end{pmatrix} = F_x \hat{e}_x + F_y \hat{e}_y + F_z \hat{e}_z$$

Komponenten



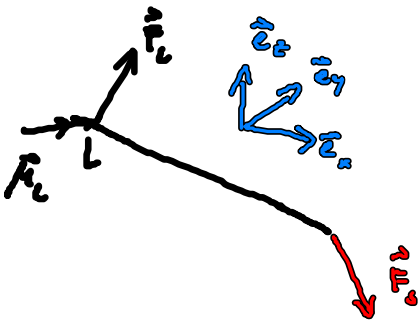
geg: Kraft im Pol sei $F_s = 300\text{N}$

ges: Lagerreaktionen

1) statische Lösung: \rightarrow Verteilungskräfte

2) vektorielle Lösung: \rightarrow Mathematik

1) FS:



2) GGB:

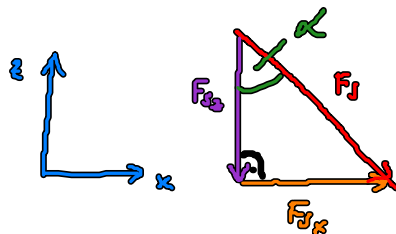
$$\sum \vec{F}_i = 0 \rightarrow \vec{F}_L = -\vec{F}$$

$$\sum \vec{M}_i = 0 \rightarrow \vec{M}_L = -\vec{M}_S$$

3) $\vec{F}_S = ?$

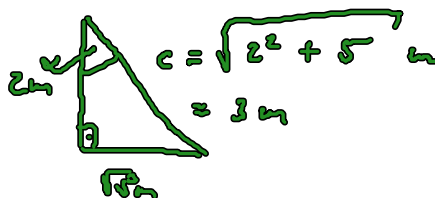
i) $\vec{F}_S = \begin{pmatrix} F_{Sx} \\ F_{Sy} \\ F_{Sz} \end{pmatrix}$

Skizze



$$F_{Sx} = F_s \sin(\alpha)$$

$$F_{Sz} = -F_s \cos(\alpha)$$



$$\sin(\alpha) = \frac{\sqrt{5}}{3}$$

$$\cos(\alpha) = \frac{2}{3}$$

$$\Rightarrow \vec{F}_s = F_s \begin{pmatrix} \frac{\sqrt{2}}{2} \\ 0 \\ \frac{\sqrt{2}}{2} \end{pmatrix}$$

ii) $\vec{F}_s = F_s \cdot \vec{e}_s$

Bedingung $|\vec{e}_s| = 1$

Ergebnis

Skizze:



$$\vec{F}_s = \begin{pmatrix} \sqrt{2}m \\ 0 \\ \sqrt{2}m \end{pmatrix}$$

$$\vec{e}_s = \frac{\vec{F}_s}{|\vec{F}_s|}$$

$$\vec{e}_s = \frac{1}{\sqrt{2}} \begin{pmatrix} \sqrt{2}m \\ 0 \\ \sqrt{2}m \end{pmatrix} = \begin{pmatrix} \frac{\sqrt{2}}{2} \\ 0 \\ \frac{\sqrt{2}}{2} \end{pmatrix} \Rightarrow \vec{F}_s = F_s \cdot \begin{pmatrix} \frac{\sqrt{2}}{2} \\ 0 \\ \frac{\sqrt{2}}{2} \end{pmatrix}$$

4.) LR:

$$\vec{F}_L = -\vec{F}_s = F_s \begin{pmatrix} -\frac{\sqrt{2}}{2} \\ 0 \\ \frac{\sqrt{2}}{2} \end{pmatrix}$$

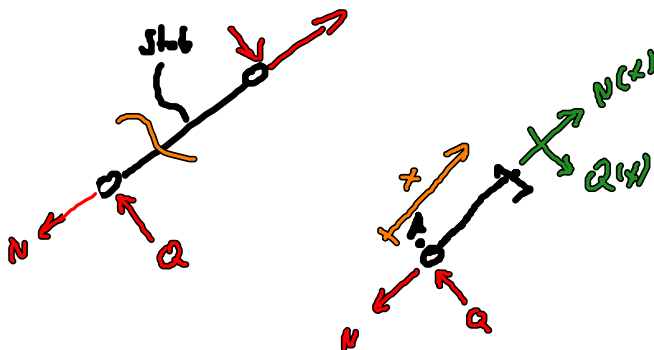
$$\vec{M}_L = -\vec{r}_s^L = -(\vec{r}_s \times \vec{F}_s) = \underbrace{-3m \vec{e}_x \times F_s \left(\frac{\sqrt{2}}{2} \vec{e}_x + \left(-\frac{\sqrt{2}}{2}\right) \vec{e}_z \right)}_{=0} = -2 \vec{e}_y$$

$$\vec{M}_L = -2m \frac{\sqrt{2}}{2} F_s \vec{e}_y = -2 \cdot F_s m \vec{e}_y = -60 \text{ Nm } \vec{e}_y$$

Fachwerke:

ideales FV:

- gegliedert
- Kräfte nur in Knoten



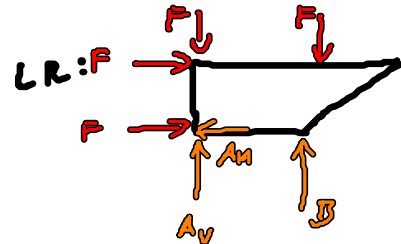
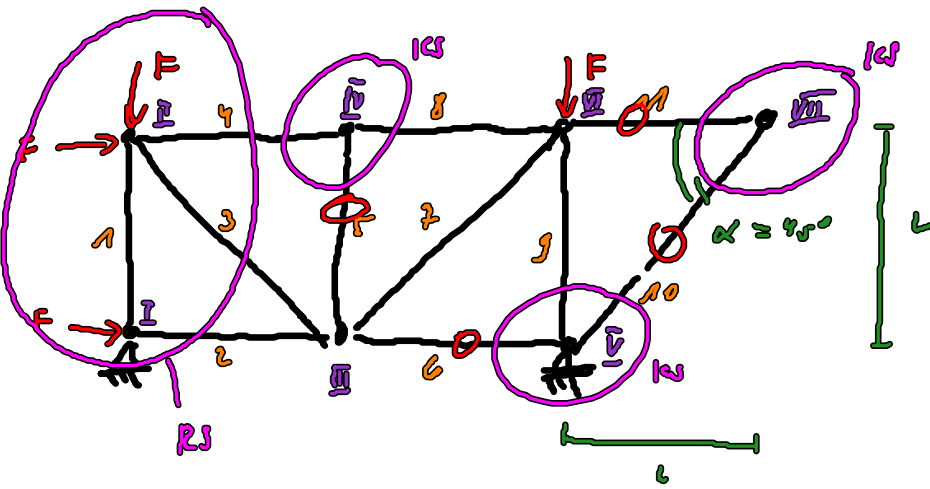
$$x: N(x) = N = \text{const.}$$

$$z: Q(x) = Q = 0$$

Skizze übertragen nur \leftarrow

Normalkräfte

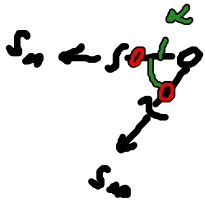
$\sum Q(x) \cdot x = 0 \Rightarrow Q(x) = 0$



GGD: $B = \frac{3}{2}F, A_V = \frac{1}{2}F, A_H = 2F$

1) Nullstelle

KS: III

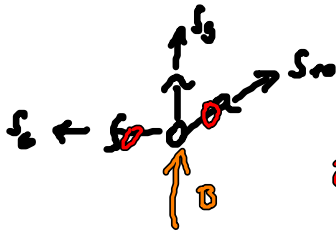


x: $0 = -S_{11} - S_{10} \cos(\alpha) \Rightarrow S_{11} = -S_{10} \cos(\alpha) = 0$

y: $0 = -S_{10} \sin(\alpha) \Rightarrow S_{10} = 0$

1. NNT-Regel

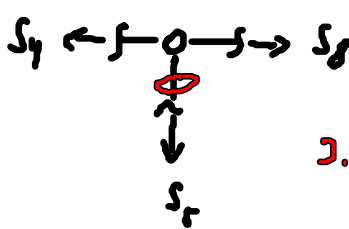
KS: IV



x: $0 = -S_6 \Rightarrow S_6 = 0$

2. NNT-Regel

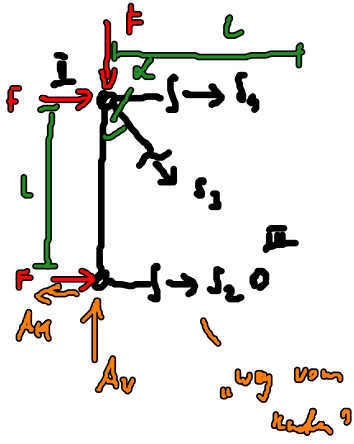
KS: V



y: $0 = -S_r \Rightarrow S_r = 0$

3. NNT-Regel

2) RITTER-Schnitt



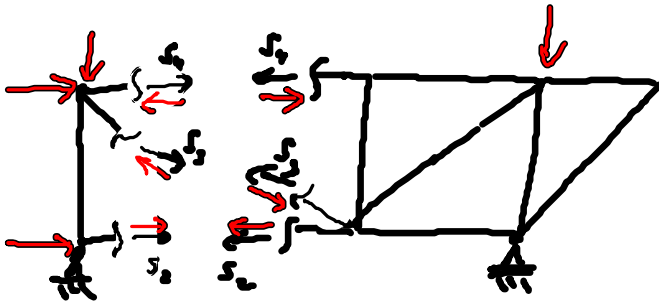
$$M^B: 0 = -A_v \cdot l - F \cdot l - S_1 \cdot l + F \cdot l$$

$$S_1 = -A_v = -\frac{1}{2}F \quad (D)$$

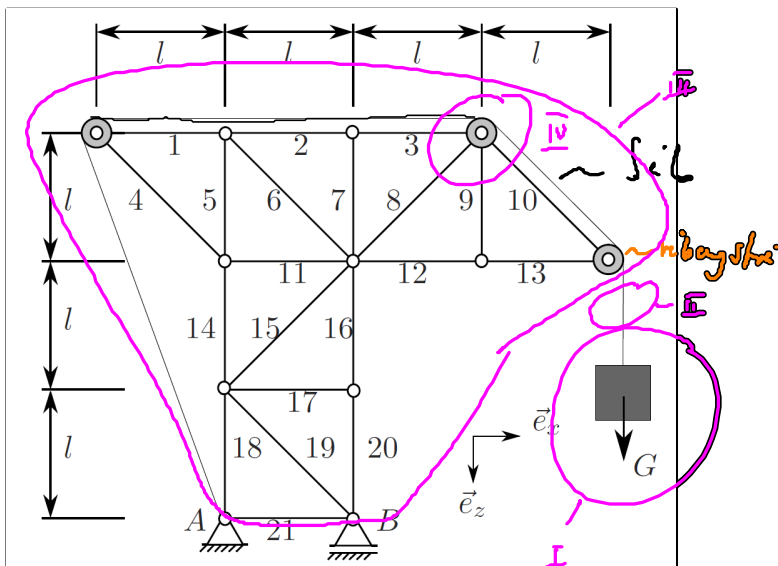
$$y: 0 = A_v - F - S_2 \cdot \frac{\sqrt{2}}{2}$$

$$S_2 = \frac{2}{\sqrt{2}}(A_v - F) = -\frac{\sqrt{2}}{2} \cdot \frac{1}{2}F = -\frac{1}{\sqrt{2}}F \quad (D)$$

$$M^B: 0 = S_2 \cdot l + F \cdot l - A_v \cdot l \Rightarrow S_2 = A_v - F = +F \quad (z)$$

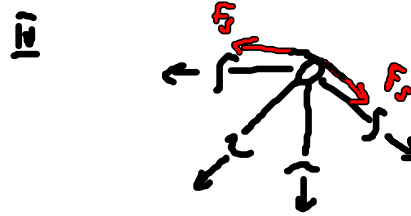
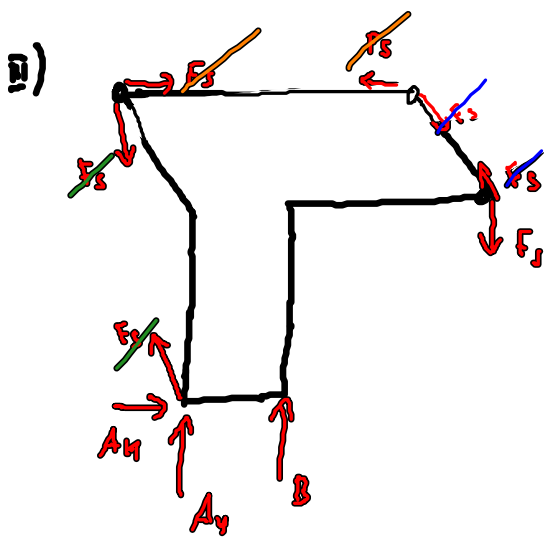
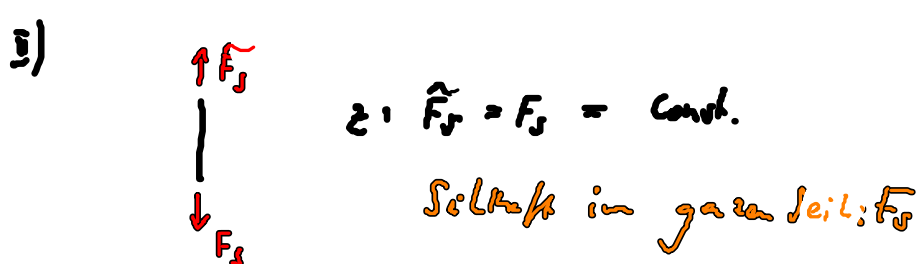
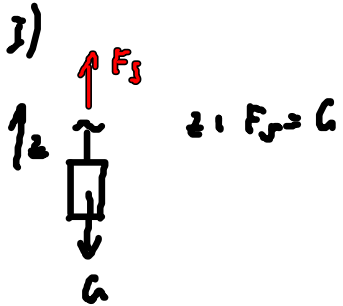


Seile im System

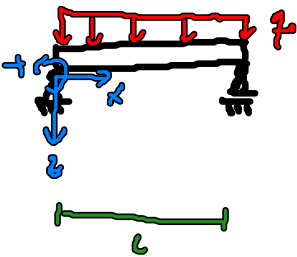


Seil:

- Nur Kräfte entlang seiner Richtung
- Nur Zugkräfte
- biegeweich



Schnittstellen



ges: Q, M

\Rightarrow SL-Differentialgleichungen

$$\frac{dQ}{dx} = Q' = -q \quad (1)$$

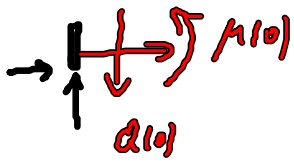
$$\frac{dM}{dx} = M' = Q \quad (2)$$

a): $Q(x) = -\int q(x) dx + C_1 = -q_0 x + \underline{C_1}$

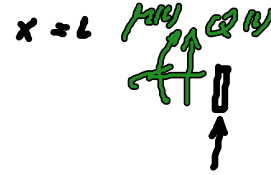
b): $M(x) = \int Q(x) dx + C_2 = -\frac{1}{2} q_0 x^2 + C_1 x + \underline{C_2}$

C_1 / C_2 aus RBen: ("Kann ich $M(x)$ oder $Q(x)$ am Rand?")

$x=0$:



$$M(0) = 0 \quad \text{RB1}$$



$$M(L) = 0 \quad \text{RB2}$$

RDm einsetzen:

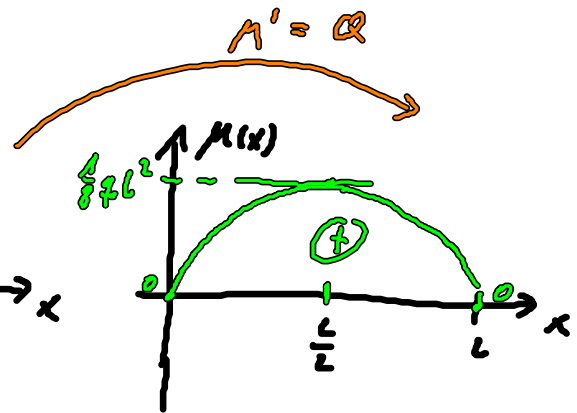
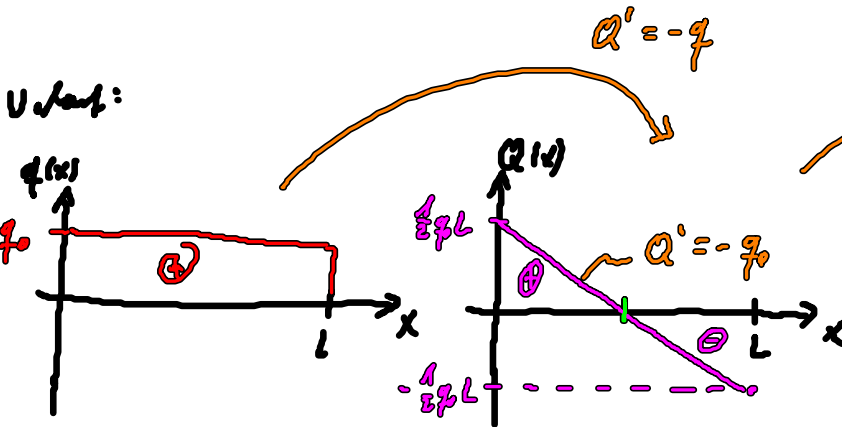
$$\text{RB1: } 0 = -\frac{1}{2} q_0 l^2 + \cancel{C_1} \cdot 0 + C_2 \Rightarrow C_2 = 0$$

$$\text{RB2: } 0 = -\frac{1}{2} q_0 l^2 + C_1 l \Rightarrow C_1 = \frac{1}{2} q_0 l$$

Ergebnis:

$$Q(x) = -q_0 x + \frac{1}{2} q_0 l = q_0 l \left(\frac{1}{2} - \frac{x}{l} \right) = q_0 l \left(\frac{1}{2} - \left(\frac{x}{l} \right) \right)$$

$$M(x) = -\frac{1}{2} q_0 x^2 + \frac{1}{2} q_0 l x = \frac{1}{2} q_0 l^2 \left(\frac{x}{l} - \frac{x^2}{l^2} \right) = \frac{1}{2} q_0 l^2 \left(\left(\frac{x}{l} \right) - \left(\frac{x}{l} \right)^2 \right)$$



$$Q(0) = \frac{1}{2} q_0 l$$

$$Q(l) = -\frac{1}{2} q_0 l$$

$$M(0) = 0$$

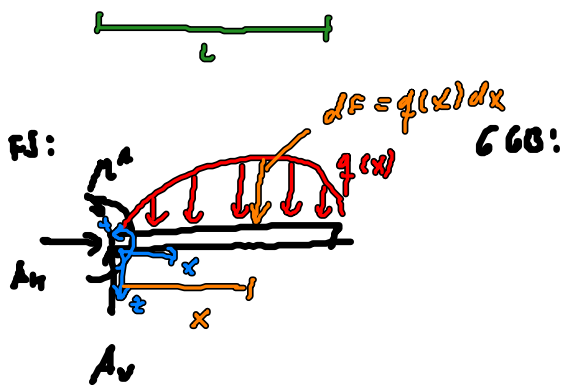
$$M(l) = 0$$

$$M\left(\frac{l}{2}\right) = \frac{1}{8} q_0 l^2$$

Sammellsg



$$q(x) = q \sin\left(\frac{\pi}{2} x\right)$$



$$\Sigma: 0 = -A_y + \int_F dF$$

$$A_y = \int_0^L q(x) dx = \int_0^L q_0 \sin\left(\frac{\pi}{2} x\right) dx$$

$$A_y = \left[-\frac{2}{\pi} q_0 \cos\left(\frac{\pi}{2} x\right) \right]_0^L$$

$$A_y = -q_0 \frac{2}{\pi} \left(\cos\left(\frac{\pi}{2}\right) - \cos\left(\frac{\pi}{2} \cdot 0\right) \right) = 2q_0 \frac{2}{\pi}$$

$$M^A: 0 = M^A - \int_M dM \Rightarrow M^A = \int_0^L x q(x) dx$$

$$M^A = -x q_0 \frac{2}{\pi} \cos\left(\frac{\pi}{2} x\right) \Big|_0^L + \int_0^L q_0 \frac{2}{\pi} \cos\left(\frac{\pi}{2} x\right) dx = q_0 \frac{L^2}{\pi}$$

$$\Rightarrow x_s = \frac{\int_0^L x q(x) dx}{\int_0^L q(x) dx} = \frac{q_0 \frac{L^2}{\pi}}{2q_0 \frac{2}{\pi}} = \frac{1}{2} L$$

Angelpunkt der Resultierenden